## **Gear Intake** Project

## **General Description**

We made walls to hold axles, and motors. On the axle we attach compliant wheels to take in the gear. We used a wooden base to act as a platform to hold the gear. We used pistons to give the mechansim to positions, which means after picking up the gear from the field, we can lift the mechanism 90 degrees.

## **Technical Specifications**





We used ultraplanetary gearbox. The gear ratio in the gear box is 16:1. We used two 1/2inch thunderhex, 4 inch compliant wheels, 3D printing filaments walls, and wood platform.

## **Further Improvement**

We would improve on the structure of the intake walls, to make the gear better slide onto the platform. We would also design the way connecting the walls differently, maybe using screws instead of threaded inserts. Also 3D print the bottom slide instead of using an exisiting plastic piece

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